A remark on left invariant metrics on compact Lie groups

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1 Introduction

The investigation of manifolds with non-negative sectional curvature is one of the classical fields of study in global Riemannian geometry. While there are few known obstruction for a closed manifold to admit metrics of non-negative sectional curvature, there are relatively few known examples and general construction methods of such manifolds (see [Z] for a detailed survey).

In this context, it is particularly interesting to investigate left invariant metrics on a compact connected Lie group G with Lie algebra \mathfrak{g} . These metrics are obtained by left translation of an inner product on \mathfrak{g} . If this metric is biinvariant then its sectional curvature is non-negative, and it is known that the set of inner products on \mathfrak{g} whose corresponding left invariant metric on G has non-negative sectional curvature is a connected cone; indeed, each such inner product can be connected to a biinvariant one by a canonical path ([T]).

In the present article, it is shown that the stretching of the biinvariant metric in the direction of a subalgebra of \mathfrak{g} almost always produces some negative sectional curvature of the corresponding left invariant metric on G. In fact, the following theorem answers a question raised in [Z, Problem 1, p.9].

Theorem 1.1 Let $H \subset G$ be compact Lie groups with Lie algebras $\mathfrak{h} \subset \mathfrak{g}$, let Q be a biinvariant inner product on \mathfrak{g} , and for t > 0 let g_t be the left invariant metric on G induced by the inner product

$$Q_t := t \ Q|_{\mathfrak{h}} + Q|_{\mathfrak{h}^{\perp}}. \tag{1}$$

If there is a t > 1 such that g_t has non-negative sectional curvature, then then the semi-simple part of \mathfrak{h} is an ideal of \mathfrak{g} .

Note that this condition is indeed optimal: if $t \leq 1$ then g_t is known to have non-negative sectional curvature, and if the semi-simple part of \mathfrak{h} is an ideal of \mathfrak{g} then g_t has non-negative sectional curvature even for $t \leq 4/3$ ([GZ]).

There is yet another reason why this result is of interest. One of the most spectacular source of examples of manifolds of non-negative sectional curvature of the last decade was given in [GZ] where it was shown that any closed cohomogeneity one manifold whose non-principal orbits have codimension at most two admit invariant metrics of non-negative sectional curvature. Their construction is

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based on glueing homogeneous disk bundles of rank ≤ 2 along a totally geodesic boundary which is equipped with a normal homogeneous metric.

The reason for this construction to work is due to the fact that the structure group of the fibers is contained in H = SO(k) where k is the rank of the bundle. If $k \le 2$, then H is abelian, so that the metrics g_t from Theorem 1.1 have non-negative sectional curvature for some t > 1.

Our result now suggests that for most subgroups $H' \subset H$, the metric on G/H' induced by the metric g_t with t > 1 from Theorem 1.1 will have some negative sectional curvature as well. Therefore, it will be difficult to find more examples of non-negatively curved metrics on homogeneous vector bundles over G/H with normal homogeneous collar. Also, note that there are examples of cohomogeneity one manifolds, including the Kervaire spheres, which do not admit invariant metric of non-negative sectional curvature at all ([GVWZ]).

2 Proof of Theorem 1.1

Let $H \subset G$, $\mathfrak{h} \subset \mathfrak{g}$, Q_t and g_t be as in Theorem 1.1, and let $\mathfrak{m} := \mathfrak{h}^{\perp}$, so that we have the orthogonal splitting

$$\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{m}.$$
 (2)

Then a calculation shows that for any s > 0 and t := s/(1+s), the multiplication map

$$(H \times G, sQ|_{\mathfrak{h}} + Q|_{\mathfrak{g}}) \longrightarrow (G, g_t)$$
 (3)

becomes a Riemannian submersion (cf. e.g. [Ch]). But $sQ|_{\mathfrak{h}}+Q|_{\mathfrak{g}}$ is a biinvariant metric on $H\times G$ which therefore has non-negative sectional curvature, and by O'Neill's formula so does Q_t . Since $Q_1=Q$ is a biinvariant metric, and any $t\in (0,1)$ can be written as t=s/(1+s) for some s>0, we conclude that Q_t has non-negative sectional curvature for all $t\leq 1$.

We shall divide the proof of Theorem 1.1 into two lemmas.

Lemma 2.1 Suppose that the metric Q_t on G has non-negative sectional curvature for some t > 1. Then for all $x, y \in \mathfrak{g}$ with [x, y] = 0 we must have $[x_{\mathfrak{h}}, y_{\mathfrak{h}}] = 0$, where $x = x_{\mathfrak{h}} + x_{\mathfrak{m}}$ and $y = y_{\mathfrak{h}} + y_{\mathfrak{m}}$ is the decomposition according to (2).

Proof. The curvature tensor R^t of the metric g_t has been calculated e.g. in [GZ]. Namely, for elements $x = x_{\mathfrak{h}} + x_{\mathfrak{m}}$ and $y = y_{\mathfrak{h}} + y_{\mathfrak{m}}$ we have

$$Q_{t}(R^{t}(x,y)y,x) = \frac{\frac{1}{4}||[x_{\mathfrak{m}},y_{\mathfrak{m}}]_{\mathfrak{m}} + t[x_{\mathfrak{h}},y_{\mathfrak{m}}] + t[x_{\mathfrak{m}},y_{\mathfrak{h}}]||_{Q}^{2}}{+ \frac{\frac{1}{4}t||[x_{\mathfrak{h}},y_{\mathfrak{h}}]||_{Q}^{2} + \frac{1}{2}t(3-2t)Q([x_{\mathfrak{h}},y_{\mathfrak{h}}],[x_{\mathfrak{m}},y_{\mathfrak{m}}]_{\mathfrak{h}}) + (1-\frac{3}{4}t)||[x_{\mathfrak{m}},y_{\mathfrak{m}}]_{\mathfrak{h}}||_{Q}^{2}}.$$

$$(4)$$

Let $x^t := tx_{\mathfrak{h}} + x_{\mathfrak{m}}$ and $y^t := ty_{\mathfrak{h}} + y_m$. Then, using that $[\mathfrak{h}, \mathfrak{m}] \subset \mathfrak{m}$, it follows that

$$[x^t, y^t]_{\mathfrak{h}} = t^2[x_{\mathfrak{h}}, y_{\mathfrak{h}}] + [x_{\mathfrak{m}}, y_{\mathfrak{m}}]_{\mathfrak{h}} \qquad \text{and} \qquad [x^t, y^t]_{\mathfrak{m}} = [x_{\mathfrak{m}}, y_{\mathfrak{m}}]_{\mathfrak{m}} + t[x_{\mathfrak{h}}, y_{\mathfrak{m}}] + t[x_{\mathfrak{m}}, y_{\mathfrak{h}}].$$

If we assume that $[x^t, y^t] = 0$, then $[x_{\mathfrak{m}}, y_{\mathfrak{m}}]_{\mathfrak{h}} = -t^2[x_{\mathfrak{h}}, y_{\mathfrak{h}}]$ and $[x_{\mathfrak{m}}, y_{\mathfrak{m}}]_{\mathfrak{m}} + t[x_{\mathfrak{h}}, y_{\mathfrak{m}}] + t[x_{\mathfrak{m}}, y_{\mathfrak{h}}] = 0$. Substituting this into (4) yields

$$Q_{t}(R^{t}(x,y)y,x) = \left(\frac{1}{4}t - \frac{1}{2}t^{3}(3-2t) + (1-\frac{3}{4}t)t^{4}\right)||[x_{\mathfrak{h}},y_{\mathfrak{h}}]||_{Q}^{2}$$

$$= -\frac{1}{4}t(t-1)^{3}(1+3t)||[x_{\mathfrak{h}},y_{\mathfrak{h}}]||_{Q}^{2}.$$
(5)

If this expression is non-negative for some t > 1, then $[x_{\mathfrak{h}}, y_{\mathfrak{h}}] = 0$. Thus, $[x_{\mathfrak{h}}^t, y_{\mathfrak{h}}^t] = t^2[x_{\mathfrak{h}}, y_{\mathfrak{h}}] = 0$ whenever $[x^t, y^t] = 0$.

Lemma 2.2 Let $\mathfrak{h} \subset \mathfrak{g}$ be a Lie subalgebra such that all $x, y \in \mathfrak{g}$ with [x, y] = 0 satisfy $[x_{\mathfrak{h}}, y_{\mathfrak{h}}] = 0$, where $x = x_{\mathfrak{h}} + x_{\mathfrak{m}}$ and $y = y_{\mathfrak{h}} + y_{\mathfrak{m}}$ is the decomposition according to (2). Then the semi-simple part of \mathfrak{h} is an ideal of \mathfrak{g} .

Proof. Let $\mathfrak{h} = \mathfrak{z}(\mathfrak{h}) \oplus \mathfrak{h}_1 \oplus \ldots \oplus \mathfrak{h}_r$ be the decomposition into the center and simple ideals. Then $[x_{\mathfrak{h}}, y_{\mathfrak{h}}] = 0$ iff $[x_{\mathfrak{h}_k}, y_{\mathfrak{h}_k}] = 0$ for all k. Also, the semi-simple part of \mathfrak{h} is an ideal of \mathfrak{g} iff $\mathfrak{h}_k \triangleleft \mathfrak{g}$ for all k. Thus, it suffices to show the lemma for all \mathfrak{h}_k , whence we shall assume for the rest of the proof that \mathfrak{h} is *simple*.

Step 1. Let $y \in \mathfrak{m}$ be such that there is an $0 \neq x \in \mathfrak{h}$ with [x,y] = 0. Then $[\mathfrak{h},y] = 0$.

For any $a \in \mathfrak{m}$ and $t \in \mathbb{R}$, we have $[Ad_{\exp(ta)}x, Ad_{\exp(ta)}y] = Ad_{\exp(ta)}[x, y] = 0$, hence by hypothesis $[(Ad_{\exp(ta)}x)_{\mathfrak{h}}, (Ad_{\exp(ta)}y)_{\mathfrak{h}}] = 0$.

But $[a,x] \in [\mathfrak{m},\mathfrak{h}] \subset \mathfrak{m}$, hence $(Ad_{\exp(ta)}x)_{\mathfrak{h}} = x + O(t^2)$, whereas $(Ad_{\exp(ta)}y)_{\mathfrak{h}} = t[a,y]_{\mathfrak{h}} + \frac{1}{2}t^2[a,[a,y]]_{\mathfrak{h}} + O(t^3)$. Therefore, for all $t \in \mathbb{R}$ we have

$$0 = \left[(Ad_{\exp(ta)}x)_{\mathfrak{h}}, (Ad_{\exp(ta)}y)_{\mathfrak{h}} \right] = t[x, [a, y]_{\mathfrak{h}}] + \frac{1}{2}t^{2}[x, [a, [a, y]]_{\mathfrak{h}}] + O(t^{3})$$

$$= t[x, [a, y]]_{\mathfrak{h}} + \frac{1}{2}t^{2}[x, [a, [a, y]]]_{\mathfrak{h}} + O(t^{3}).$$
(6)

The last equation follows since for all $x \in \mathfrak{h}$ and $z = z_{\mathfrak{h}} + z_{\mathfrak{m}}$ we have $[x, z_{\mathfrak{h}}] \in \mathfrak{h}$ and $[x, z_{\mathfrak{m}}] \in \mathfrak{m}$, whence $[x, z_{\mathfrak{h}}] = [x, z]_{\mathfrak{h}}$. Thus, we must have $[x, [a, y]]_{\mathfrak{h}} = 0$ for all $a \in \mathfrak{m}$. On the other hand, if $a \in \mathfrak{h}$ then $[x, [a, y]] \in [\mathfrak{h}, [\mathfrak{h}, \mathfrak{m}]] \subset \mathfrak{m}$, hence $[x, [a, y]]_{\mathfrak{h}} = 0$ for all $a \in \mathfrak{h}$ as well, and therefore,

$$0 = Q([x, [\mathfrak{g}, y]], \mathfrak{h}) = Q(\mathfrak{g}, [[x, \mathfrak{h}], y]), \text{ i.e., } [[x, \mathfrak{h}], y] = 0.$$
 (7)

By [S, Lemma 4.4] and the simplicity of \mathfrak{h} , it follows that \mathfrak{h} is the linear span of x, $[x,\mathfrak{h}]$ and $[[x,\mathfrak{h}],[x,\mathfrak{h}]]$. Since [x,y]=0, and $[[x,\mathfrak{h}],y]=0$ by (7), this together with the Jacobi identity now implies that $[\mathfrak{h},y]=0$ as claimed.

Step 2. Let $y \in \mathfrak{m}$ be such that $[\mathfrak{h}, y] = 0$. Let $\mathfrak{g}' \triangleleft \mathfrak{g}$ and $\mathfrak{g}'' \triangleleft \mathfrak{g}$ be the ideals generated by \mathfrak{h} and y, respectively. Then $Q(\mathfrak{g}', \mathfrak{g}'') = 0$ and $[\mathfrak{g}', \mathfrak{g}''] = 0$. In particular, $Q(\mathfrak{g}', y) = 0$

First, note the it suffices to show that $Q(\mathfrak{h},\mathfrak{g}'')=0$. For if this is the case, it then follows that $Q(ad(\mathfrak{g})^n(\mathfrak{h}),\mathfrak{g}'')=Q(\mathfrak{h},ad(\mathfrak{g})^n(\mathfrak{g}''))=Q(\mathfrak{h},\mathfrak{g}'')=0$, which implies that $Q(\mathfrak{g}',\mathfrak{g}'')=0$. Hence, $Q([\mathfrak{g}',\mathfrak{g}''],\mathfrak{g})=Q(\mathfrak{g}',[\mathfrak{g}'',\mathfrak{g}])=Q(\mathfrak{g}',\mathfrak{g}'')=0$ so that $[\mathfrak{g}',\mathfrak{g}'']=0$ follows.

By [S, Lemma 4.4], \mathfrak{g}'' is the linear span of y, $[\mathfrak{g}, y]$ and $[\mathfrak{g}, [\mathfrak{g}, y]]$. Since $y \in \mathfrak{m}$, we have $Q(y, \mathfrak{h}) = 0$, and $Q([\mathfrak{g}, y], \mathfrak{h}) = Q(\mathfrak{g}, [\mathfrak{h}, y]) = 0$ by hypothesis. Thus, $Q(\mathfrak{h}, \mathfrak{g}'') = 0$ will be demonstrated once we show that $Q([\mathfrak{g}, [\mathfrak{g}, y]], \mathfrak{h}) = 0$.

For a fixed $h \in \mathfrak{h}$, we define the bilinear form α_h on \mathfrak{g} by

$$\alpha_h(a,b) := Q([a,[b,y]],h).$$

Thus, our goal shall be to show that $\alpha_h = 0$ for all $h \in \mathfrak{h}$. Note that $\alpha_h(a,b) - \alpha_h(b,a) = Q([a,[b,y]] - [b,[a,y]],h) = Q([[a,b],y],h) = -Q([a,b],[h,y]) = 0$ by hypothesis, hence α_h is symmetric. If $b \in \mathfrak{h}$, then [b,y] = 0 by hypothesis, so that $\alpha_h(\mathfrak{g},\mathfrak{h}) = 0$.

By or hypothesis and step 1, (6) holds for all $x \in \mathfrak{h}$, thus the vanishing of the t^2 -coefficient of (6) implies that

$$0 = Q([\mathfrak{h}, [a, [a, y]], \mathfrak{h})) = Q([a, [a, y]], [\mathfrak{h}, \mathfrak{h}]) = Q([a, [a, y]], \mathfrak{h}) \text{ for all } a \in \mathfrak{m}.$$

Thus, $\alpha_h(a,a) = 0$ for all $a \in \mathfrak{m}$ and therefore, $\alpha_h = 0$ for all $h \in \mathfrak{h}$ as asserted.

Step 3. $\mathfrak{h} \triangleleft \mathfrak{g}$.

Let $\mathfrak{g}' \lhd \mathfrak{g}$ be the ideal generated by \mathfrak{h} . By steps 1 and two, it follows that there cannot be an $0 \neq x \in \mathfrak{h}$ and $0 \neq y \in \mathfrak{m} \cap \mathfrak{g}'$ with [x, y] = 0. This immediately implies that $rk(\mathfrak{h}) = rk(\mathfrak{g}')$.

If $rk(\mathfrak{h}) = rk(\mathfrak{g}') = 1$, then $\mathfrak{h} = \mathfrak{g}' \triangleleft \mathfrak{g}$ and we are done. If $rk(\mathfrak{h}) \geq 2$ then we can choose linearly independent elements $x_1, x_2 \in \mathfrak{h}$ with $[x_1, x_2] = 0$. If $\mathfrak{m} \cap \mathfrak{g}' \neq 0$, then the restrictions of ad_{x_i} to $\mathfrak{m} \cap \mathfrak{g}'$ have common eigenspaces, i.e., there is an orthogonal decomposition

$$\mathfrak{m} \cap \mathfrak{g}' = V_1 \oplus \ldots \oplus V_m$$

into two-dimensional subspaces V_k on which both ad_{x_i} act by a multiple of rotation by a right angle. Therefore, for each k, there is a suitable $0 \neq x^k \in span(x_1, x_2) \subset \mathfrak{h}$ such that $[x^k, V_k] = 0$ which is a contradiction. Therefore, $\mathfrak{m} \cap \mathfrak{g}' = 0$, i.e., $\mathfrak{h} = \mathfrak{g}' \triangleleft \mathfrak{g}$.

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